



MODELING FOR WHAT PURPOSE?

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System dynamics does not impose models on people for the first time—models are already present in everything we do. One does not have a family or corporation or city or country in one’s head. Instead, one has observations and assumptions about those systems. Such observations and assumptions constitute mental models, which are then used as a basis for action.

The ultimate success of a system dynamics investigation depends on a clear initial identification of an important purpose and objective. Presumably a system dynamics model will organize, clarify, and unify knowledge. The model should give people a more effective understanding about an important system that has previously exhibited puzzling or controversial behavior. In general, influential system dynamics projects are those that change the way people think about a system. Mere confirmation that current beliefs and policies are correct may be satisfying but hardly necessary, unless there are differences of opinion to be resolved. Changing and unifying viewpoints means that the relevant mental models are being altered.

Unifying Knowledge

Complex systems defy intuitive solutions. Even a third-order, linear differential equation is unsolvable by inspection. Yet, important situations in management, economics, medicine, and social behavior usually lose reality if simplified to less than fifth-order nonlinear dynamic systems.

Attempts to deal with nonlinear dynamic systems using ordinary processes of description and debate lead to internal inconsistencies. Underlying assumptions may have been left unclear and contradictory, and mental models are often logically incomplete. Resulting behavior is likely to be contrary to that implied by the assumptions being made about underlying system structure and governing policies.

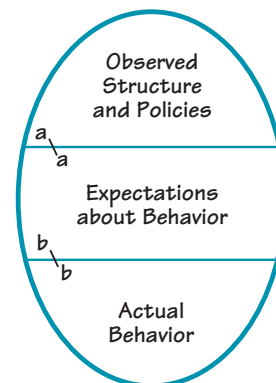
System dynamics modeling can be effective because it builds on the reliable part of our understanding of systems while compensating for the unreliable part. The system dynamics procedure untangles several threads that cause confusion in ordinary debate: underlying assumptions (structure, policies, and parameters), and implied behavior. By considering assumptions independently from resulting behavior,

there is less inclination for people to differ on assumptions (on which they actually can agree) merely because they initially disagree with the dynamic conclusions that might follow.

If we divide knowledge of systems into three categories, we can illustrate wherein lie the strengths and weaknesses of mental models and simulation models (see “Three Categories of Information”). The top of the figure represents knowledge about structure and policies; that is, about the elementary parts of a system. This is local non-dynamic knowledge. It describes information available at each decision-making point. It identifies who controls each part of a system. It reveals how pressures and crises influence decisions. In general, information about structure and policies is far more reliable, and is more often seen in the same way by different people, than is generally assumed. It is only necessary to dig out the information by using system dynamics insights about how to organize structural information to address a particular set of dynamic issues.

The middle of the figure represents assumptions about how the system will behave, based on the observed structure and policies in the top section. This

THREE CATEGORIES OF INFORMATION



There are three categories of information about a system: knowledge about structure and policies; assumptions about how the system will behave based on the observed structure and policies; and the actual system behavior as it is observed in real life. The usual discrepancy is across the boundary a-a: expected behavior is not consistent with the known structure and policies in the system.

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